The groupoids of adaptable separated graphs and their type semigroups (I)

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Universidad de Cádiz

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P. ARA, J. BOSA, E.P., A. SIMS, **The groupoids of adaptable separated graphs and their type semigroups**

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arXiv:1904.05197v2 (math.RA).





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- The strategy
- 2 Monoids and graphs
- 3 Adaptable separated graphs
- Inverse semigroups
- 5 The tight groupoid of an adaptable separated graph

The problem The strategy

Outline



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The problem The strategy

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Used to determine the stably finite versus purely infinite dichotomy for $C_r^*(\mathcal{G})$.



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The Tarski notion of paradoxicality, transfered to the *K*-theoretic context, played a major role in recent approaches:

- In the case of actions of a discrete group *G* on the Cantor set *X*, Rørdam & Sierakowski introduced a semigroup *S*(*X*, *G*) –an analog of Tarski's type semigroup– and tied the pure infiniteness of C(X) ×_r G to the existence of states on *S*(*X*, *G*).
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 Rainone & Sims extended the idea, by defining a semigroup S(G) associated to a étale groupoid G (see also Bönicke & Li's work).

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Realization Problem for von Neumann regular rings (exchange rings) [Goodearl]:

Which kind of conical refinement monoids are realizable as $\mathcal{V}(R)$ for a suitable von Neumann regular ring (exchange ring)?

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Advances: it is possible to construct such a ring for monoids associated to (directed) graphs E.

[Ara-Moreno-P]: monoids M(E) associated to graphs are representable as \mathcal{V} -monoids for Leavitt path algebras $L_K(E)$.

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To solve the Realization problem in this case, the trick is to take suitable "universal localizations" $Q_{\cal K}(E)$.

These algebras are von Neumann regular rings. Moreover, $\mathcal{V}(Q_K(E)) \cong M(E)$.

Exist examples of countable, conical refinement monoids out of the scope of these construction [Ara-Perera-Werung].

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CONNECTION: It is known $\mathcal{V}(L_K(E)) \cong M(E) \cong \operatorname{Typ}(\mathcal{G}_E)$.

A possibility for extending the above result is to work with a monoid M such that there is an algebra A and a groupoid \mathcal{G}_A with:

• $M \cong \operatorname{Typ}(\mathcal{G}_A).$

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What we will show in these two talks is that the previous schema works for conical, finitely generated refinement monoids.



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Let me outline which is the strategy we follow for fill all the gaps.

(1) Basic tool: use separated graphs (E, C), because for any countable conical monoid M there exists (E, C) such that $M \cong M(E, C)$ [Ara-Goodearl].

(2) For each conical, finitely generated refinement monoid M, construct a finite *I*-system \mathcal{J} so that $M \cong M(\mathcal{J})$ [Ara-P].

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(3) Given any finite *I*-system \mathcal{J} , construct an special separated graph (E, C) such that $M(E, C) \cong M(\mathcal{J})$ (this is an <u>adaptable</u> separated graph).

(4) Use the set of basic partial isometries of $L_K(E, C)$, and enlarge it for constructing an inverse semigroup S(E, C).

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(5) Determine the topological space of tight filters $\hat{\mathcal{E}}_{\text{tight}}$ associated to the semilattice of idempotents of S(E, C), and define a (partial) action $S(E, C) \frown \hat{\mathcal{E}}_{\text{tight}}$.

(6) Construct the Exel's tight groupoid $\mathcal{G}(E, C)$ for this partial action, and determine some basic properties.

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IN THE SECOND TALK

(7) Construct the Steinberg algebra $A_K(\mathcal{G}(E, C))$, and show that it is isomorphic to the algebra $\mathcal{S}_K(E, C)$ defined for generators & relations of S(E, C).

(8) Prove that $\operatorname{Typ}(\mathcal{G}(E,C)) \cong M(E,C)$.

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(9) Construct a von Neumann regular universal localization $Q_K(E,C)$ of $\mathcal{S}_K(E,C)$.

(10) Use a deconstruction (pullback) - reconstruction (pushout) procedure to show that $\mathcal{V}(Q_K(E,C)) \cong \text{Typ}(\mathcal{G}(E,C))$.

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Definition

A commutative monoid M is *conical* if, for all x, y in M, x + y = 0 only when x = y = 0.

Definition

M is a *refinement monoid* if, for all *a*, *b*, *c*, *d* in *M* such that a + b = c + d, there exist *w*, *x*, *y*, *z* in *M* such that a = w + x, b = y + z, c = w + y and d = x + z.

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A basic example of a refinement monoid is the monoid

$$M(E) = \left\langle a_v(v \in E^0) : a_v = \sum_{e \in s^{-1}(v)} a_{r(e)} \right\rangle$$

associated to a countable row-finite graph E.

If $x, y \in M$, $x \leq y$ if exists $z \in M$ such that x + z = y.

Definition

An element $p \in M$ is a *prime* if p is not invertible in M, and, whenever $p \leq a + b$ for $a, b \in M$, then either $p \leq a$ or $p \leq b$.

Definition

A commutative monoid M is primely generated if every non-invertible $x \in M$ is a finite sum of prime elements of M.

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An element $x \in M$ is:

[Bookfield]: any element of a primely generated refinement monoid is either free or regular.

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An element $x \in M$ is:



free if $nx \leq mx$ implies $n \leq m$, for $n, m \in \mathbb{N}$.

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An element $x \in M$ is:

- regular if $2x \le x$.
- 2) free if $nx \leq mx$ implies $n \leq m$, for $n, m \in \mathbb{N}$.

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Let M be a finitely generated conical refinement monoid. We will express M in terms of "generalized graphs":

Definition (Ara-Goodearl)

A separated graph is a pair (E, C) where E is a graph, $C = \bigsqcup_{v \in E^0} C_v$, and C_v is a partition of $s^{-1}(v)$ (into pairwise disjoint nonempty subsets) for every vertex v.

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The constructions we introduce revert to existing ones in case $C_v = \{s^{-1}(v)\}$ for each $v \in E^0$. We refer to a *non-separated* graph in that situation.

We assume throughout that (E, C) is *finitely separated*, i.e., $|X| < \infty$ for all $X \in C$.



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Let (E, C) be a separated graph. Its monoid is

$$M(E,C) = \left\langle a_v(v \in E^0) : a_v = \sum_{e \in X} a_{r(e)}, \forall X \in C_v, \forall v \in E^0 \right\rangle.$$

Theorem (Ara-Goodearl)

Every finitely generated conical monoid is M(E, C) for a suitable separated graph (E, C).

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Every finitely generated conical monoid is M(E, C) for a suitable separated graph (E, C).

Definition

The Leavitt path algebra of the separated graph (E, C) over a field K is the *-algebra $L_K(E, C)$ with generators $\{v, e \mid v \in E^0, e \in E^1\}$, subject to the following relations: (V) $vv' = \delta_{v,v'}v$ for all $v, v' \in E^0$, (E) s(e)e = er(e) = e for all $e \in E^1$, (SCK1) $e^*e' = \delta_{e,e'}r(e)$ for all $e, e' \in X, X \in C$, and (SCK2) $v = \sum_{e \in X} ee^*$ for every $X \in C_v, v \in E^0$.

Theorem (Ara-Goodearl)

For any separated graph (E, C),

$\mathcal{V}(L_K(E,C)) \cong M(E,C).$

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[Pierce]: Every conical primely generated antisymmetric monoid can be represented as a semilattice (a poset with an order-absorbing relation).

[Dobbertin]: Every primely generated conical regular refinement monoid can be represented as a semilattice of finitely generated abelian groups (a sort of partial order of finitely generated abelian groups).

[Pierce]: Every conical primely generated antisymmetric monoid can be represented as a semilattice (a poset with an order-absorbing relation).

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[Ara-P]: Any primely generated refinement monoid M can be represented as a sort of semilattice of free & regular archimedean semigroups, via an *I*-system \mathcal{J} .

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This construction generalizes Pierce's and Dobbertin's constructions.

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Definition

Let $I = (I, \leq)$ be a poset. An *I*-system

$$\mathcal{J} = (I, \leq, (G_i)_{i \in I}, \varphi_{ji} \, (i < j))$$

is given by the following data:

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- (a) A partition $I = I_{\text{free}} \sqcup I_{\text{reg}}$.
- (b) A family $\{G_i\}_{i \in I}$ of abelian groups, with:
 - (1) For $i \in I_{reg}$, set $M_i = G_i$, and $G_i = G_i = M_i$.
- (c) A family of semigroup homomorphisms $\varphi_{ji} \colon M_i \to G_j$ for all i < j, satisfying suitable properties.

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We attach to each finite *I*-system \mathcal{J} a conical, finitely generated <u>refinement</u> monoid $M(\mathcal{J})$.

 $M(\mathcal{J})$ is the monoid generated by the M_i s, with defining relations

 $x + y = x + \varphi_{ji}(y), \quad i < j, x \in M_j, y \in M_i.$

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$$x + y = x + \varphi_{ji}(y), \quad i < j, x \in M_j, y \in M_i.$$

Theorem (Ara-P)

Let *M* be a conical, primely generated refinement monoid. Then, there exists an *I*-system \mathcal{J} such that $M \cong M(\mathcal{J})$.

Corollary (Ara-P)

Let M be a conical, finitely generated refinement monoid. Then, there exists a finite *I*-system \mathcal{J} such that $M \cong M(\mathcal{J})$.

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Corollary (Ara-P)

Let *M* be a conical, finitely generated refinement monoid. Then, there exists a finite *I*-system \mathcal{J} such that $M \cong M(\mathcal{J})$.

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Given any finite *I*-system \mathcal{J} , we attach to it a finitely separated graph (E, C) such that

 $M(E,C) \cong M(\mathcal{J}).$

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This is done as follows.
The idea is to take a finitely separated graph (E, C) such that you can decompose it using the antisymmetrization $I = I_{\text{free}} \sqcup I_{\text{reg}}$ of (E^0, \leq) and a family of separated subgraphs $\{(E_p, C_p)\}_{p \in I}$ of E, so that:

- $E^0 = \bigsqcup_{p \in I} E^0_p.$
- All the connecting maps between E_ps go downwards on I.
- The form of (E_p, C_p) allows to recover the monoid M_t when computing its associated monoid.



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- ② All the connecting maps between E_p s go downwards on I.
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- 2 All the connecting maps between E_p s go downwards on *I*.
- **③** The form of (E_p, C_p) allows to recover the monoid M_i when computing its associated monoid.

To be precise, an *adaptable separated graph* is a finitely separated graph (E, C) s.t:

(1) $I = E^0/\sim$ is the antisymmetrization of E^0 with respect to the pre-order $v \ge w$ iff there is a path $v \to w$. Then I is finite and $I = I_{\text{free}} \sqcup I_{\text{reg}}$.

(2) $E^0 = \bigsqcup_{p \in I} E_p^0$, where E_p is a strongly connected row-finite graph if $p \in I_{\text{reg}}$ and $E_p^0 = \{v^p\}$ is a single vertex if $p \in I_{\text{free}}$.



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(3) For $v \in E_p^0$ with $p \in I_{\text{reg}}$, we have $|C_v| = 1$.

(4) For $p \in I_{\text{free}}$, we have that $s^{-1}(v^p) = \emptyset$ if and only if p is minimal in I. If p is not minimal there is a positive integer k(p) such that $C_{v^p} = \{X_1^{(p)}, \ldots, X_{k(p)}^{(p)}\}$, where each $X_i^{(p)}$ is of the form

$$X_i^{(p)} = \{ \alpha(p, i), \beta(p, i, 1), \beta(p, i, 2), \dots, \beta(p, i, g(p, i)) \},\$$

for some $g(p,i) \ge 1$, where $\alpha(p,i)$ is a loop, i.e., $s(\alpha(p,i)) = r(\alpha(p,i)) = v^p$, and $r(\beta(p,i,t)) \in E_q^0$ for q < p.

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Theorem

Let \mathcal{J} be a finite *I*-system. Then there is an adaptable separated graph (E, C) such that

$M(E,C) \cong M(\mathcal{J}).$

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Theorem

- If (E, C) is an adaptable separated graph, then M(E, C) is a refinement monoid.
- **(a)** For any finitely generated conical refinement monoid M, there exists an adaptable separated graph (E, C) such that $M \cong M(E, C)$.

So, adaptable separated graphs provide a suitable combinatorial input for our construction.

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- The problem
- The strategy
- 2 Monoids and graphs
- 3 Adaptable separated graphs
- Inverse semigroups
- 5 The tight groupoid of an adaptable separated graph

Given an adaptable separated graph as before, we want to associate a groupoid to it.

We will follow Exel's construction of the tight groupoid of an inverse semigroup, so that we need first to get an inverse semigroup S based on the paths on E.

For this, we also consider Cuntz-Krieger relations (SCK1)-(SCK2) as before ...

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Definition

A semigroup T is an *inverse semigroup* if

- for every x in T, there exists a unique $x^* \in T$, such that $xx^*x = x$ and $x^*xx^* = x^*$,
- there exists a (necessarily unique) element 0 ∈ T, called the zero element, such that x0 = 0x = 0, for all x in T.

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Introduction	
Monoids and graphs	
Adaptable separated graphs	
Inverse semigroups	
The tight groupoid of an adaptable separated graph	

If T is an inverse semigroup, then the set of idempotents of T, $\mathcal{E} = \mathcal{E}(T)$, is a semilattice with ordering $e \leq f$ if and only if ef = e, and $e \wedge f = ef$.

Notation

If $p \in I$ is **non-minimal** and **free**, we denote by σ^p the map $\mathbb{N} \to \mathbb{N}$ given by

$$\sigma^p(i) = i + k(p) - 1.$$

Moreover, if $1 \le j \le k(p)$, we denote by σ_j^p the unique bijective, non-decreasing map from $\{1, \ldots, k(p)\} \setminus \{j\}$ onto $\{1, \ldots, k(p) - 1\}$.

Definition

Given an adaptable separated graph (E, C), denote by S(E, C) the *-semigroup (with 0) generated by

$$E^0 \cup E^1 \cup \{(t^v_i)^{\pm} \mid i \in \mathbb{N}, v \in E^0\}$$

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with the defining relations given below, except B1(ii)(d) and B2(1)(ii).

RELATIONS

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BLOCK 1: Tor all $v, w \in E^0$, we have $v \cdot w = \delta_{v,w}v$ and $v = v^*$. For all $e \in E^1$, we have: e = s(e)e = er(e) $e^*e = r(e)$ $e^*f = \delta_{e,f}r(e)$ if $e, f \in X \subseteq C_{s(e)}$. $v = \sum_{e \in X} ee^*$, for $X \in C_v, v \in E^0$.

BLOCK 2: (1) For each free prime $p \in I$ and i = 1, ..., k(p), we have: (1) For each free prime $p \in I$ and i = 1, ..., k(p), we have: (1) $\alpha(p, i)^* \alpha(p, i) = v^p$ (2) $\alpha(p, i) \alpha(p, i) = v^p$ (3) $\alpha(p, i) \alpha(p, i)^* = v^p - \sum_{t=1}^{g(p,i)} \beta(p, i, t) \beta(p, i, t)^*$ (3) For $i \neq j$, $\alpha(p, i) \alpha(p, j) = \alpha(p, j) \alpha(p, i)$, and $\alpha(p, i) \alpha(p, j)^* = \alpha(p, j)^* \alpha(p, i)$. (3) $\beta(p, i, s)^* \beta(p, j, t) = 0$ if either $i \neq j$, or i = j and $s \neq t$. (3) $\alpha(p, i)^* \beta(p, i, t) = 0 = \beta(p, i, t)^* \alpha(p, i)$ for all $1 \leq i \leq k(s)$

 $\label{eq:alpha} \begin{array}{l} \textcircled{0} \quad \alpha(p,i)^*\beta(p,i,t) = 0 = \beta(p,i,t)^*\alpha(p,i) \text{ for all } 1 \leq i \leq k(p) \\ \text{ and all } 1 \leq t \leq g(p,i). \end{array}$



(2) For the $\{t_i^v\}$, we impose the following relations:

() For each $v \in E^0$, $\{(t_i^v)^{\pm} : i \in \mathbb{N}\}$ is a family of mutually commuting elements such that

$$vt_i^v = t_i^v = t_i^v v, \qquad t_i^v (t_i^v)^{-1} = v = (t_i^v)^{-1} t_i^v, \qquad (t_i^v)^* = (t_i^v)^{-1}.$$

(1) If $p \in I$ is regular, $e \in E^1$ is such that $s(e) \in E_p^0$ and $i \in \mathbb{N}$,

$$t_i^{s(e)}e = et_i^{r(e)}.$$

If $p \in I$ is free, $i \in \mathbb{N}$, $1 \le j \le k(p)$ and $1 \le s \le g(p, j)$,

$$(t_i^{v^p})^{\pm}\beta(p,j,s) = \beta(p,j,s)(t_{\sigma^p(i)}^{r(\beta(p,j,s))})^{\pm},$$

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If
$$p \in I$$
 is free, $i \neq j$, and $1 \leq s \leq g(p, j)$,
 $\alpha(p, i)\beta(p, j, s) = \beta(p, j, s)t_{\sigma_j^p(i)}^{r(\beta(p, j, s))}$

and

(iv)

$$\alpha(p,i)^*\beta(p,j,s) = \beta(p,j,s)(t_{\sigma_j^p(i)}^{r(\beta(p,j,s))})^{-1}.$$

We provide a different description of S(E, C). This will be given via the paths that one can intuitively associate to any adaptable separated graph.

Roughly, a finite path is as follows: consider a sequence of elements $p_1 > p_2 > \ldots > p_n$ of the poset *I*, and for each *i* a path γ_i in E_{p_i} ; we form a finite path by connecting the γ_i together via the connectors β . Diagrammatically, we may write

$$p_1 \curvearrowright^{\beta_{1,2}} p_2 \curvearrowright^{\beta_{2,3}} \ldots \curvearrowright^{\beta_{n-1,n}} p_n.$$

We now define the monomials as the possible multiplicative expressions one can form using generators (excluding connectors) corresponding to a given prime. They will be denoted by $\mathbf{m}(p)$ for $p \in I$. Namely,

(1) if p is a **free** prime, we define

$$\mathbf{m}(p) = (t_{i_1}^{v^p})^{d_1} \dots (t_{i_r}^{v^p})^{d_r} \prod_{j=1}^{k(p)} \alpha(p,j)^{k_j} (\alpha(p,j)^*)^{l_j}$$

for $d_1, \ldots, d_r \in \mathbb{Z} \setminus \{0\}, r \ge 0, k_j, l_j \ge 0$

(2) if p is a **regular** prime, we define

$$\mathbf{m}(p) = (t_{i_1}^v)^{d_1} \dots (t_{i_r}^v)^{d_r} \gamma \nu^*,$$

where γ, ν are paths of finite length in E_p satisfying $s(\gamma) = v$, $v \in E_p^0$, and $r(\gamma) = r(\nu)$.

Definition

S is the union of $\{0\}$ and the set of all triples $(\gamma, \mathbf{m}(p), \eta)$, where γ, η are finite paths, $\mathbf{m}(p)$ is a monomial at some prime $p \in I$, and $r(\gamma) = s(\mathbf{m}(p)), r(\eta) = r(\mathbf{m}(p))$.

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So, *S* consists of combinations $\gamma \mathbf{m}(p)\eta^*$ of a finite path, a monomial and the star of a finite path.

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So, *S* consists of combinations $\gamma \mathbf{m}(p)\eta^*$ of a finite path, a monomial and the star of a finite path.

Proposition

Let (E, C) be an adaptable separated graph. Then, there is a natural *-isomorphism $S(E, C) \cong S$.

The idempotents in S are of the form $\gamma {\bf m}(p)\gamma^*;$ moreover, the idempotents commute. So

Proposition

Let (E, C) be an adaptable separated graph. Then, S(E, C) is an inverse semigroup.

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Let (E, C) be an adaptable separated graph. Then, S(E, C) is an inverse semigroup.
An inverse semigroup is E^* -unitary if given an idempotent e and an element s, if e = se then s is idempotent.

Proposition

Let (E, C) be an adaptable separated graph. Then the associated inverse semigroup S(E, C) is E^* -unitary.

This guarantees that the groupoid we will construct is Hausdorff.

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5 The tight groupoid of an adaptable separated graph

Definition

A groupoid \mathcal{G} is an small category in which every homomorphism is an isomorphism. We will denote by $\mathcal{G}^{(0)}$ its set of units, and by $r, s : \mathcal{G} \to \mathcal{G}^{(0)}$ the range and source maps $r(\gamma) = \gamma \gamma^*$ and $s(\gamma) = \gamma^* \gamma$.

Definition

A *topological groupoid* is a groupoid endowed with a topology under which multiplication and inversion are continuous maps; in particular, r and s are continuous maps.

Definition

A topological groupoid \mathcal{G} is said to be *étale* if r (and so s) is a local homeomorphism from \mathcal{G} to $\mathcal{G}^{(0)}$.

If \mathcal{G} is étale, then $\mathcal{G}^{(0)}$ is open. We will always asume that our groupoids are étale, locally compact, and $\mathcal{G}^{(0)}$ is Hausdorff in the relative topology.

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Definition

A locally compact étale groupoid \mathcal{G} is said to be *ample* if $\mathcal{G}^{(0)}$ is totally disconnected.

This is equivalent to assume that the topology of \mathcal{G} has a basis of open compact bisections. Here, a bisection is a subset $U \subseteq \mathcal{G}$ such that r and s are injective on U.

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Definition

Let T be an inverse semigroup, and let \mathcal{E} be its semilattice of idempotents. A filter in \mathcal{E} is a nonempty subset $\eta \subseteq \mathcal{E}$ such that:

- $0 \not\in \eta,$
- 2 closed under \land ,

We denote the set of filters by $\widehat{\mathcal{E}}_0.$ This is a locally compact totally disconnected Hausdorff space when equipped with the cylinder topology:

Given finite subsets $X, Y \subseteq \mathcal{E}$, consider the set

$$U(X,Y) = \{ \eta \in \hat{\mathcal{E}}_0 : X \subseteq \eta, \ Y \subseteq \mathcal{E} \setminus \eta \}.$$

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Then each U(X, Y) is an open set and the collection of all such is easily seen to form a basis for the topology of $\hat{\mathcal{E}}_0$.

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Then each U(X, Y) is an open set and the collection of all such is easily seen to form a basis for the topology of $\hat{\mathcal{E}}_0$.

Definition

A filter η is an *ultrafilter* if it is not properly contained in another filter. We denote $\widehat{\mathcal{E}}_{\infty} \subseteq \widehat{\mathcal{E}}_0$ the space of ultrafilters.

Definition

The set $\widehat{\mathcal{E}}_{\mathsf{tight}}$ of *tight filters* is the closure of $\widehat{\mathcal{E}}_\infty$ into $\widehat{\mathcal{E}}_0.$

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Definition

We define a standard partial action of T on $\widehat{\mathcal{E}}_0$ as follows:

• For each
$$e \in \mathcal{E}$$
, $D_e^\beta = \{\eta \in \widehat{\mathcal{E}}_0 : e \in \eta\}$,

$$\begin{array}{ll} \textbf{ iven } s \in T, \\ \beta_s : D_{s^*s}^{\beta} & \longrightarrow D_{ss^*}^{\beta} \\ \eta & \longrightarrow \beta_s(\eta) = \{ f \in \mathcal{E} : f \geq ses^* \text{ for every } e \in \eta \} \end{array}$$

 β restricts to an action of T on ultrafilters and on tight filters.

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Consider the transformation groupoid $T \times \widehat{\mathcal{E}}_{tight}$.

The elements are the pairs (s, ω) such that $\omega \in \mathsf{Dom}(s) = D_{s^*s}^{\beta}$.

We fix the germ relation: $(s, \omega) \sim (t, \eta)$ if $\omega = \eta$ and there exists an idempotent $e \leq t, s$ with $\omega \in \text{Dom}(e)$ such that se = te.

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Definition (Tight groupoid of the inverse semigroup T)

Define
$$\mathcal{G}_{\text{tight}}(T) = T \times \widehat{\mathcal{E}}_{\text{tight}} / \sim$$
, with:
1 $d([s,x]) = x$ and $r([s,x]) = \beta_s(x)$,
2 $[s,z] \cdot [t,x] = [st,x]$ if and only if $z = \beta_t(x)$
3 $[s,x]^{-1} = [s^*, \beta_s(x)]$,
3 $\mathcal{G}_{\text{tight}}^{(0)}(T) = \{[e,x] : e \in \mathcal{E}\} \cong \widehat{\mathcal{E}}_{\text{tight}}$

 $\mathcal{G}_{\mathsf{tight}}(T)$ is ample, but in general is neither Hausdorff nor amenable.

Definition (Tight groupoid of the inverse semigroup T)

Define
$$\mathcal{G}_{\text{tight}}(T) = T \times \widehat{\mathcal{E}}_{\text{tight}} / \sim$$
, with:
• $d([s, x]) = x \text{ and } r([s, x]) = \beta_s(x),$
• $[s, z] \cdot [t, x] = [st, x] \text{ if and only if } z = \beta_t(x),$
• $[s, x]^{-1} = [s^*, \beta_s(x)],$
• $\mathcal{G}_{\text{tight}}^{(0)}(T) = \{[e, x] : e \in \mathcal{E}\} \cong \widehat{\mathcal{E}}_{\text{tight}}$

 $\mathcal{G}_{\text{tight}}(T)$ is ample, but in general is neither Hausdorff nor amenable.

Given $s \in T$, $U \subseteq D_{s^*s}$ open subset, the set

 $\Theta(s,U)=\{[s,\xi]:\xi\in U\}$

is an open compact bisection.

In fact, the set $\{\Theta(s, U) : s \in T, U \subseteq D_{s^*s}\}$ is a basis of the topology of $\mathcal{G}_{\text{tight}}(T)$.

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Let us identify what happens in the case of T being S(E, C).





Let γ be a finite path. A **semifinite path** μ starting at γ is one of the following:

(1) If $r(\gamma) = v^p$, with p a free prime, then

$$u = \gamma \prod_{j=1}^{k(p)} \alpha(p, j)^{k_j},$$

where $0 \le k_j \le \infty$ for all $j \in \{1, ..., k(p)\}$. We say that μ is an infinite path if $k_j = \infty$ for all $j \in \{1, ..., k(p)\}$.

(2) If $r(\gamma) = v$ with $v \in E_p^0$ and p a regular prime, then

$$\mu = \gamma \lambda,$$

where λ is either a finite or an infinite path in the graph E_p . We say that μ is an **infinite path** if λ is an infinite path in E_p .

Theorem

Let S be the collection of all semifinite paths. Then

- There is a bijective correspondence $\varphi \colon S \to \hat{\mathcal{E}}_0$.
- 2 φ restricts to a bijection between the set of infinite paths and the set $\hat{\mathcal{E}}_{\infty}$ of ultrafilters.
- Solution The space $\hat{\mathcal{E}}_{\infty}$ of ultrafilters is closed in the space $\hat{\mathcal{E}}_{0}$ of filters. Consequently, $\hat{\mathcal{E}}_{\infty} = \hat{\mathcal{E}}_{tight}$.

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Definition

We denote by \mathcal{P} the set of semifinite paths of the form $\mu = \gamma \lambda$, where γ is a finite path, and λ is a path of finite length in the component of a regular prime, or $\lambda = \prod_{j=1}^{k(p)} \alpha(p, j)^{k_j}$ for $k_j \in \mathbb{Z}^+$, $1 \leq j \leq k(p)$ for a free prime p.

Notice that every $e \in \mathcal{E}$ is of the form $e(\mu)$ for a unique $\mu \in \mathcal{P}$. Accordingly, elements of \mathcal{P} will be called \mathcal{E} -paths.

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For $\mu \in \mathcal{P}$, write

$$\mathcal{Z}(\mu) = \{ \eta \in \hat{\mathcal{E}}_{\infty} \mid \mu \mu^* \in \eta \}.$$

Depending on the situation, $\mathcal{Z}(\mu)$ might also be denoted by the idempotent it determines, i.e., $\mathcal{Z}(e(\mu))$. Notice that $\mathcal{Z}(\mu) = \mathcal{U}(\{\mu\mu^*\}, \emptyset) \cap \hat{\mathcal{E}}_{\infty}$.

Corollary

The space $\hat{\mathcal{E}}_{\infty}$ of ultrafilters admits a basis of compact open subsets, namely the family $\{\mathcal{Z}(\mu)\}_{\mu\in\mathcal{P}}$. Moreover, every compact open subset of $\hat{\mathcal{E}}_{\infty}$ is a finite disjoint union of sets of the form $\mathcal{Z}(\mu)$, for $\mu \in \mathcal{P}$.

Corollary

The set $\{\Theta(\mu\mu^*, \mathcal{Z}(\mu)) : \mu \in \mathcal{P}\}$ is a basis of open compact bisections of the tight groupoid $\mathcal{G}(E, C) := \mathcal{G}_{tight}(S(E, C)).$

Since S(E, C) is E^* -unitary, we conclude by results of [Exel]

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Proposition

If (E, C) is a finitely separated graph, then $\mathcal{G}(E, C)$ is a Hausdorff groupoid.

By using a "graph-goupoid" type picture of $\mathcal{G}(E,C),$ we are able to prove

Proposition

Let (E, C) be an adaptable separated graph. The groupoid $\mathcal{G}(E, C)$ is amenable.

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The groupoids of adaptable separated graphs and their type semigroups (I)

Enrique Pardo

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Higher rank graphs: geometry, symmetry, dynamics ICMS, July 16, 2019.

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